

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

APPLICATION FOR LETTERS PATENT

**Methods and Systems for Implementing Dynamic
Properties on Objects that Support Only Static
Properties**

Inventor(s):

Daniel J. Miller
David Maymudes

1 **TECHNICAL FIELD**

2
3 This invention generally relates to processing media content and, more
4 particularly, to a system and related interfaces facilitating the processing of media
5 content.

6 **BACKGROUND**

7
8 Recent advances in computing power and related technology have fostered
9 the development of a new generation of powerful software applications. Gaming
10 applications, communications applications, and multimedia applications have
11 particularly benefited from increased processing power and clocking speeds.
12 Indeed, once the province of dedicated, specialty workstations, many personal
13 computing systems now have the capacity to receive, process and render
14 multimedia objects (e.g., audio and video content). While the ability to display
15 (receive, process and render) multimedia content has been around for a while, the
16 ability for a standard computing system to support true multimedia editing
17 applications is relatively new.

18 In an effort to satisfy this need, Microsoft Corporation introduced an
19 innovative development system supporting advanced user-defined multimedia
20 editing functions. An example of this architecture is presented in US Patent No.
21 5,913, 038 issued to Griffiths and commonly owned by the assignee of the present
22 invention, the disclosure of which is expressly incorporated herein by reference.

23 In the '038 patent, Griffiths introduced the an application program interface
24 which, when exposed to higher-level development applications, enables a user to
25 graphically construct a multimedia processing project by piecing together a

1 collection of "filters" exposed by the interface. The interface described therein is
2 referred to as a filter graph manager. The filter graph manager controls the data
3 structure of the filter graph and the way data moves through the filter graph. The
4 filter graph manager provides a set of component object model (COM) interfaces
5 for communication between a filter graph and its application. Filters of a filter
6 graph architecture are preferably implemented as COM objects, each
7 implementing one or more interfaces, each of which contains a predefined set of
8 functions, called methods. Methods are called by an application program or other
9 component objects in order to communicate with the object exposing the interface.
10 The application program can also call methods or interfaces exposed by the filter
11 graph manager object.

12 Filter graphs work with data representing a variety of media (or non-media)
13 data types, each type characterized by a data stream that is processed by the filter
14 components comprising the filter graph. A filter positioned closer to the source of
15 the data is referred to as an upstream filter, while those further down the
16 processing chain is referred to as a downstream filter. For each data stream that
17 the filter handles it exposes at least one virtual pin (i.e., distinguished from a
18 physical pin such as one might find on an integrated circuit). A virtual pin can be
19 implemented as a COM object that represents a point of connection for a
20 unidirectional data stream on a filter. Input pins represent inputs and accept data
21 into the filter, while output pins represent outputs and provide data to other filters.
22 Each of the filters include at least one memory buffer, wherein communication of
23 the media stream between filters is often accomplished by a series of "copy"
24 operations from one filter to another.
25

09/18/2000 10:00:00

As introduced in Griffiths, a filter graph has three different types of filters: source filters, transform filters, and rendering filters. A source filter is used to load data from some source; a transform filter processes and passes data; and a rendering filter renders data to a hardware device or other locations (e.g., saved to a file, etc.). An example of a filter graph for a simplistic media rendering process is presented with reference to Fig. 1.

Fig. 1 graphically illustrates an example filter graph for rendering media content. As shown, the filter graph 100 is comprised of a plurality of filters 102-114, which read, process (transform) and render media content from a selected source file. As shown, the filter graph includes each of the types of filters described above, interconnected in a linear fashion.

Products utilizing the filter graph have been well received in the market as it has opened the door to multimedia editing using otherwise standard computing systems. It is to be appreciated, however, that the construction and implementation of the filter graphs are computationally intensive and expensive in terms of memory usage. Even the most simple of filter graphs requires and abundance of memory to facilitate the copy operations required to move data between filters. Complex filter graphs can become unwieldy, due in part to the linear nature of prior art filter graph architecture. Moreover, it is to be appreciated that the filter graphs themselves consume memory resources, thereby compounding the issue introduced above.

Thus, what is required is a filter graph architecture which reduces the computational and memory resources required to support even the most complex of multimedia projects. Indeed, what is required is a dynamically reconfigurable

1 multimedia editing system and related methods, unencumbered by the limitations
2 described above. Just such a system and methods are disclosed below.

3 4 **SUMMARY**

5
6 Methods and systems of simulating dynamic properties on computer-
7 implemented objects that do not support dynamic properties are described. In one
8 embodiment, one or more first objects that do not support dynamic properties are
9 provided. One or more second programmable objects are provided and are
10 programmed to effect property value changes on the objects that do not support
11 dynamic properties. The programmable objects can be programmed using data
12 structures that, in one embodiment, comprise an array of one or more sets of data
13 structures. Each data structure set is associated with a property whose value is
14 desired to be changed. The data structure set can define a new property value, a
15 time at which the property value is to be changed, and how to effect the property
16 value change. The programmable object(s) is pre-programmed with the data
17 structures and knows when to call the first objects so that they can change their
18 properties. In one embodiment, the programmable objects are employed in the
19 context of multi-media project editing software that permits a user to build a
20 multi-media project using multiple different digital source streams.

21 22 **BRIEF DESCRIPTION OF THE DRAWINGS**

23
24 The same reference numbers are used throughout the figures to reference
25 like components and features.

1 Fig. 1 is a graphical representation of a conventional filter graph
2 representing a user-defined development project.

3 Fig. 2 is a block diagram of a computing system incorporating the teachings
4 of the described embodiment.

5 Fig. 3 is a block diagram of an example software architecture incorporating
6 the teachings of the described embodiment.

7 Fig. 4 is a graphical illustration of an example software-enabled matrix
8 switch, according to an exemplary embodiment.

9 Fig. 5 is a graphical representation of a data structure comprising a
10 programming grid to selectively couple one or more of a scalable plurality of input
11 pins to a scalable plurality of output pins of the matrix switch filter, in accordance
12 with one aspect of the described embodiment.

13 Fig. 6 is a graphical illustration denoting shared buffer memory between
14 filters, according to one aspect of the described embodiment.

15 Fig. 7 is a flow chart of an example method for generating a filter graph, in
16 accordance with one aspect of the described embodiment.

17 Fig. 8 is a flow chart of an example method for negotiating buffer
18 requirements between at least two adjacent filters, according to one aspect of the
19 described embodiment.

20 Fig. 9 graphically illustrates an overview of a process that takes a user-
21 defined editing project and composites a data structure that can be used to program
22 the matrix switch.

23 Fig. 10 graphically illustrates the project of Fig. 9 in greater detail.
24
25

Fig. 12 illustrates a graphic representation of an exemplary data structure that represents the project of Fig. 10, according to one described embodiment.

Figs. 13-18 graphically illustrate various states of a matrix switch programming grid at select points in processing the project of Figs. 9 and 10 through the matrix switch, in accordance with one described embodiment.

Fig. 19 is a flow chart of an example method for processing media content, in accordance with one described embodiment.

Fig. 20 illustrates an example project with a transition and an effect, in accordance with one described embodiment.

Fig. 21 shows an exemplary data structure in the form of a hierarchical tree that represents the project of Fig. 20.

Figs. 22 and 23 graphically illustrate an example matrix switch programming grid associated with the project of Fig. 20 at select points in time, according to one described embodiment.

Fig. 24 shows an example matrix switch dynamically generated and configured as the grid of Figs. 22 and 23 was being processed, in accordance with one described embodiment.

Fig. 25 shows an exemplary project in accordance with one described embodiment.

Fig. 26 graphically illustrates an example audio editing project, according to one described embodiment.

Fig. 27 depicts an example matrix switch programming grid associated with the project of Fig. 26.

Fig. 28 shows an example matrix switch dynamically generated and configured in accordance with the programming grid of Fig. 27 to perform the project of Fig. 26, according to one described embodiment.

Fig. 29 illustrates an exemplary media processing project incorporating another media processing project as a composite, according to yet another described embodiment.

Fig. 30 graphically illustrates an example data structure in the form of a hierarchical tree structure that represents the project of Fig. 29.

Figs 31-36 graphically illustrate various matrix switch programming grid states at select points in generating and configuring the matrix switch to implement the media processing of Fig. 29.

Fig. 38 illustrates an example matrix switch suitable for use in the media processing project of Fig. 29, according to one described embodiment.

Fig. 38a graphically illustrates an example data structure in the form of a hierarchical tree structure that represents a project that is useful in understanding composites in accordance with the described embodiments.

Fig. 39 is a flow diagram that describes steps in a method in accordance with one described embodiment.

1 **DETAILED DESCRIPTION**

2 **Related Applications**

3 This application is related to the following commonly-filed U.S. Patent
4 Applications, all of which are commonly assigned to Microsoft Corp., the
5 disclosures of which are incorporated by reference herein:
6

- 7 *Sub*
8 *af*
- Application Serial No. _____, entitled "An Interface and Related Methods for Reducing Source Accesses in a Development System", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-643US;
 - Application Serial No. _____, entitled "A System and Related Interfaces Supporting the Processing of Media Content", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-629US;
 - Application Serial No. _____, entitled "A System and Related Methods for Reducing Source Filter Invocation in a Development Project", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-631US;
 - Application Serial No. _____, entitled "A System and Related Methods for Reducing Memory Requirements of a Media Processing System", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-632US;
 - Application Serial No. _____, entitled "A System and Related Methods for Reducing the Instances of Source Files in a Filter Graph", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-633US;
 - Application Serial No. _____, entitled "An Interface and Related Methods for Dynamically Generating a Filter Graph in a Development System", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-634US;
 - Application Serial No. _____, entitled "A System and Related Methods for Processing Audio Content in a Filter Graph", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-639US;
 - Application Serial No. _____, entitled "A System and Methods for Generating an Managing Filter Strings in a Filter Graph", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-642US;

09731892-120600

Application Serial No. _____, entitled "Methods and Systems for Processing Media Content", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-640US;

- Application Serial No. _____, entitled "Systems for Managing Multiple Inputs and Methods and Systems for Processing Media Content", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-635US;
- Application Serial No. _____, entitled "Methods and Systems for Implementing Dynamic Properties on Objects that Support Only Static Properties", naming Daniel J. Miller and David Maymudes as inventors, and bearing attorney docket number MS1-638US;
- Application Serial No. _____, entitled "Methods and Systems for Efficiently Processing Compressed and Uncompressed Media Content", naming Daniel J. Miller and Eric H. Rudolph as inventors, and bearing attorney docket number MS1-630US;
- Application Serial No. _____, entitled "Methods and Systems for Effecting Video Transitions Represented By Bitmaps", naming Daniel J. Miller and David Maymudes as inventors, and bearing attorney docket number MS1-637US;
- Application Serial No. _____, entitled "Methods and Systems for Mixing Digital Audio Signals", naming Eric H. Rudolph as inventor, and bearing attorney docket number MS1-636US; and
- Application Serial No. _____, entitled "Methods and Systems for Processing Multi-media Editing Projects", naming Eric H. Rudolph as inventor, and bearing attorney docket number MS1-641US.

Various described embodiments concern an application program interface associated with a development system. According to one example implementation, the interface is exposed to a media processing application to enable a user to dynamically generate complex media processing tasks, e.g., editing projects. In the discussion herein, aspects of the invention are developed within the general context of computer-executable instructions, such as program modules, being executed by one or more conventional computers. Generally, program modules include routines, programs, objects, components, data structures,

1 etc. that perform particular tasks or implement particular abstract data types.
2 Moreover, those skilled in the art will appreciate that the invention may be
3 practiced with other computer system configurations, including hand-held devices,
4 personal digital assistants, multiprocessor systems, microprocessor-based or
5 programmable consumer electronics, network PCs, minicomputers, mainframe
6 computers, and the like. In a distributed computer environment, program modules
7 may be located in both local and remote memory storage devices. It is noted,
8 however, that modification to the architecture and methods described herein may
9 well be made without deviating from spirit and scope of the present invention.
10 Moreover, although developed within the context of a media processing system
11 paradigm, those skilled in the art will appreciate, from the discussion to follow,
12 that the application program interface may well be applied to other development
13 system implementations. Thus, the media processing system described below is
14 but one illustrative implementation of a broader inventive concept.

15 16 **Example System Architecture**

17 **Fig. 2** illustrates an example of a suitable computing environment 200 on
18 which the system and related methods for processing media content may be
19 implemented.

20 It is to be appreciated that computing environment 200 is only one example
21 of a suitable computing environment and is not intended to suggest any limitation
22 as to the scope of use or functionality of the media processing system. Neither
23 should the computing environment 200 be interpreted as having any dependency
24 or requirement relating to any one or combination of components illustrated in the
25 exemplary computing environment 200.

In certain implementations, the system and related methods for processing media content may well be described in the general context of computer-executable instructions, such as program modules, being executed by a computer. Generally, program modules include routines, programs, objects, components, data structures, etc. that perform particular tasks or implement particular abstract data types. The media processing system may also be practiced in distributed computing environments where tasks are performed by remote processing devices that are linked through a communications network. In a distributed computing environment, program modules may be located in both local and remote computer storage media including memory storage devices.

In accordance with the illustrated example embodiment of Fig. 2 computing system 200 is shown comprising one or more processors or processing units 202, a system memory 204, and a bus 206 that couples various system components including the system memory 204 to the processor 202.

Bus 206 is intended to represent one or more of any of several types of bus structures, including a memory bus or memory controller, a peripheral bus, an

1 accelerated graphics port, and a processor or local bus using any of a variety of
2 bus architectures. By way of example, and not limitation, such architectures
3 include Industry Standard Architecture (ISA) bus, Micro Channel Architecture
4 (MCA) bus, Enhanced ISA (EISA) bus, Video Electronics Standards Association
5 (VESA) local bus, and Peripheral Component Interconnects (PCI) bus also
6 known as Mezzanine bus.

7 Computer 200 typically includes a variety of computer readable media.
8 Such media may be any available media that is locally and/or remotely accessible
9 by computer 200, and it includes both volatile and non-volatile media, removable
10 and non-removable media.

11 In Fig. 2, the system memory 204 includes computer readable media in the
12 form of volatile, such as random access memory (RAM) 210, and/or non-volatile
13 memory, such as read only memory (ROM) 208. A basic input/output system
14 (BIOS) 212, containing the basic routines that help to transfer information
15 between elements within computer 200, such as during start-up, is stored in ROM
16 208. RAM 210 typically contains data and/or program modules that are
17 immediately accessible to and/or presently be operated on by processing unit(s)
18 202.

19 Computer 200 may further include other removable/non-removable,
20 volatile/non-volatile computer storage media. By way of example only, Fig. 2
21 illustrates a hard disk drive 228 for reading from and writing to a non-removable,
22 non-volatile magnetic media (not shown and typically called a "hard drive"), a
23 magnetic disk drive 230 for reading from and writing to a removable, non-volatile
24 magnetic disk 232 (e.g., a "floppy disk"), and an optical disk drive 234 for reading
25 from or writing to a removable, non-volatile optical disk 236 such as a CD-ROM,

The drives and their associated computer-readable media provide nonvolatile storage of computer readable instructions, data structures, program modules, and other data for computer 200. Although the exemplary environment described herein employs a hard disk 228, a removable magnetic disk 232 and a removable optical disk 236, it should be appreciated by those skilled in the art that other types of computer readable media which can store data that is accessible by a computer, such as magnetic cassettes, flash memory cards, digital video disks, random access memories (RAMs), read only memories (ROM), and the like, may also be used in the exemplary operating environment.

A number of program modules may be stored on the hard disk 228, magnetic disk 232, optical disk 236, ROM 208, or RAM 210, including, by way of example, and not limitation, an operating system 214, one or more application programs 216 (e.g., multimedia application program 224), other program modules 218, and program data 220. In accordance with the illustrated example embodiment of Fig. 2, operating system 214 includes an application program interface embodied as a render engine 222. As will be developed more fully below, render engine 222 is exposed to higher-level applications (e.g., 216) to automatically assemble filter graphs in support of user-defined development projects, e.g., media processing projects. Unlike conventional media processing systems, however, render engine 222 utilizes a scalable, dynamically reconfigurable matrix switch to reduce filter graph complexity, thereby reducing the computational and memory resources required to complete a development

project. Various aspects of the innovative media processing system represented by a computer 200 implementing the innovative render engine 222 will be developed further, below.

Continuing with Fig. 2, a user may enter commands and information into computer 200 through input devices such as keyboard 238 and pointing device 240 (such as a “mouse”). Other input devices may include a audio/video input device(s) 253, a microphone, joystick, game pad, satellite dish, serial port, scanner, or the like (not shown). These and other input devices are connected to the processing unit(s) 202 through input interface(s) 242 that is coupled to bus 206, but may be connected by other interface and bus structures, such as a parallel port, game port, or a universal serial bus (USB).

A monitor 256 or other type of display device is also connected to bus 206 via an interface, such as a video adapter 244. In addition to the monitor, personal computers typically include other peripheral output devices (not shown), such as speakers and printers, which may be connected through output peripheral interface 246.

Computer 200 may operate in a networked environment using logical connections to one or more remote computers, such as a remote computer 250. Remote computer 250 may include many or all of the elements and features described herein relative to computer 200 including, for example, render engine 222 and one or more development applications 216 utilizing the resources of render engine 222.

As shown in Fig. 2, computing system 200 is communicatively coupled to remote devices (e.g., remote computer 250) through a local area network (LAN) 251 and a general wide area network (WAN) 252. Such networking environments

In accordance with the illustrated example implementation of Fig. 3, render engine 222 is presented comprising source filter(s) 304A-N, transform filter(s) 306A-N and render filter 310, coupled together utilizing virtual pins to facilitate a user-defined media processing project. According to one implementation, the filters of system 300 are similar to the filters exposed in conventional media processing systems. According to one implementation, however, filters are not coupled via such interface pins. Rather, alternate implementations are envisioned wherein individual filters (implemented as objects) make calls to other objects, under the control of the render engine 222, for the desired input. Unlike conventional systems, however, render engine 222 exposes a scalable, dynamically reconfigurable matrix switch filter 308, automatically generated and dynamically configured by render engine 222 to reduce the computational and memory resource requirements often associated with development projects. As introduced above, the pins (input and/or output) are application interface(s) designed to communicatively couple other objects (e.g., filters).

In accordance with the example implementation of a media processing system, an application communicates with an instance of render engine 222 when the application 216 wants to process streaming media content. Render engine 222 selectively invokes and controls an instance of filter graph manager (not shown) to automatically create a filter graph by invoking the appropriate filters (e.g., source,

transform and rendering).As introduced above, the communication of media content between filters is achieved by either (1) coupling virtual output pins of one filter to the virtual input pins of requesting filter; or (2) by scheduling object calls between appropriate filters to communicate the requested information. As shown, source filter 304 receives streaming data from the invoking application or an external source (not shown). It is to be appreciated that the streaming data can be obtained from a file on a disk, a network, a satellite feed, an Internet server, a video cassette recorder, or other source of media content. As introduced above, transform filter(s) 306 take the media content and processes it in some manner, before passing it along to render filter 310. As used herein, transform filter(s) 306 are intended to represent a wide variety of processing methods or applications that can be performed on media content. In this regard, transform filter(s) 306 may well include a splitter, a decoder, a sizing filter, a transition filter, an effects filter, and the like. The function of each of these filters is described more fully in the Griffiths application, introduced above, and generally incorporated herein by reference. The transition filter, as used herein, is utilized by render engine 222 to transition the rendered output from a first source to a second source. The effect filter is selectively invoked to introduce a particular effect (e.g., fade, wipe, audio distortion, etc.) to a media stream.

In accordance with one aspect of the embodiment, to be described more fully below, matrix switch filter 308 selectively passes media content from one or more of a scalable plurality of input(s) to a scalable plurality of output(s). Moreover, matrix switch 308 also supports implementation of a cascaded architecture utilizing feedback paths, i.e., wherein transform filters 306B, 306C, etc. coupled to the output of matrix switch 308 are dynamically coupled to one or

Typically, media processed through source, transform and matrix switch filters are ultimately passed to render filter 310, which provides the necessary interface to a hardware device, or other location that accepts the renderer output format, such as a memory or disk file, or a rendering device.

Fig. 4 is a graphical illustration of an example software-enabled matrix switch 308, according to one example embodiment of the present invention. As shown, the matrix switch 308 is comprised of a scalable plurality of input(s) 402 and a scalable plurality of output(s) 404, wherein any one or more of the input(s) 402 may be iteratively coupled to any one or more of the output(s) 404, based on the content of the matrix switch programming grid 406, automatically generated by render engine 222. According to an alternate implementation introduced above, switch matrix 308 is programmed by render engine 222 to dynamically generate object calls to communicate media content between filters. In addition, according to one implementation, matrix switch 308 includes a plurality of input/output (I/O) buffers 408, as well as means for maintaining source, or media time 410 and/or timeline, or project time 412. It is to be appreciated, however, that in alternate implementations matrix switch 308 does not maintain both source and project times, relying on an upstream filter to convert between these times. As will be developed more fully below, matrix switch 308 dynamically couples one or more of the scalable plurality of inputs 402 to one or more of the scalable plurality of outputs 404 based, at least in part, on the media time 410 and/or the project time 412 and the content of matrix switch programming grid 406. In this regard, matrix

switch 308 may be characterized as time-aware, supporting such advanced editing features as searching/seeking to a particular point (e.g., media time) in the media content, facilitating an innovative buffering process utilizing I/O buffers 408 to facilitate look-ahead processing of media content, and the like. Thus, it will be appreciated given the discussion to follow that introduction of the matrix switch 308 provides a user with an editing flexibility that was heretofore unavailable in a personal computer-based media processing system.

As introduced above, the inputs 402 and outputs 404 of matrix switch 308 are interfaces which facilitate the time-sensitive routing of data (e.g., media content) in accordance with a user-defined development project. Matrix switch 308 has a scalable plurality of inputs 402 and outputs 404, meaning that the number of inputs 402 and outputs 404 are individually generated to satisfy a given editing project. Insofar as each of the inputs/outputs (I/O) has an associated transfer buffer (preferably shared with an adjacent filter) to communicate media content, the scalability of the input/output serves to reduce the overall buffer memory consumed by an editing project. According to one implementation, output 1 is generally reserved as a primary output, e.g., coupled to a rendering filter (not shown).

According to one implementation, for each input 402 and output 404, matrix switch 308 attempts to be the allocator, or manager of the buffer associated with the I/O(s) shared with adjacent filters. One reason is to ensure that all of the buffers are of the same size and share common attributes so that a buffer associated with any input 402 may be shared with any output 404, thereby reducing the need to copy memory contents between individual buffers associated with such inputs/outputs. If matrix switch 308 cannot be an allocator for a given

1 output (404), communication from an input (402) to that output is performed using
2 a conventional memory copy operation between the individual buffers associated
3 with the select input/output.

4 As introduced above, the matrix switch programming grid 406 is
5 dynamically generated by render engine 222 based, at least in part, on the user-
6 defined development project. As will be developed below, render engine 222
7 invokes an instance of filter graph manager to assemble a tree structure of an
8 editing project, noting dependencies between source, filters and time to
9 dynamically generate the programming grid 406. A data structure comprising an
10 example programming grid 406 is introduced with reference to Fig. 5, below.

11 Turning briefly to **Fig. 5**, a graphical representation of a data structure
12 comprising an example programming grid 406 is presented, in accordance with
13 one embodiment of the present invention. In accordance with the illustrated
14 example embodiment of Fig. 5, programming grid 406 is depicted as a two-
15 dimensional data structure comprising a column along the y-axis 502 of the grid
16 denoting input pins associated with a content chain (e.g., series of filters to process
17 media content) of the development project. The top row along the x-axis 504 of
18 the data structure denotes project time. With these grid "borders", the body 506 of
19 the grid 406 is populated with output pin assignments, denoting which input pin is
20 coupled to which output pin during execution of the development project. In this
21 way, render engine 222 dynamically generates and facilitates matrix switch 308.
22 Those skilled in the art will appreciate, however, that data structures of greater or
23 lesser complexity may well be used in support of the programming grid 406
24 without deviating from the spirit and scope of the present invention.
25

Returning to Fig. 4, matrix switch 308 is also depicted with a plurality of input/output buffers 408, shared among all of the input(s)/output(s) (402, 404) to facilitate advanced processing features. That is, while not required to implement the core features of matrix switch 308, I/O buffers 408 facilitate a number of innovative performance enhancing features to improve the performance (or at least the user's perception of performance) of the processing system, thereby providing an improved user experience. According to one implementation, I/O buffers 408 are separate from the buffers assigned to each individual input and output pin in support of communication through the switch. According to one implementation, I/O buffers 408 are primarily used to foster look-ahead processing of the project. Assume, for example, that a large portion of the media processing project required only 50% of the available processing power, while some smaller portion required 150% of the available processing power. Implementation of the shared I/O buffers 408 enable filter graph manager to execute tasks ahead of schedule and buffer this content in the shared I/O buffers 408 until required. Thus, when execution of the filter graph reaches a point where more than 100% of the available processing power is required, the processing system can continue to supply content from the I/O buffers 408, while the system completes execution of the CPU-intensive tasks. If enough shared buffer space is provided, the user should never know that some tasks were not performed in real-time. According to one implementation, shared buffers 408 are dynamically split into two groups by render engine 222, a first group supports the input(s) 402, while a second (often smaller) group is used in support of a primary output (e.g., output pin 1) to facilitate a second, independent output processing thread. The use of an independent output buffers the render engine from processing delays that might occur in upstream and/or downstream

As introduced above, the filter graph is time-aware in the sense that media (source) time and project execution time are maintained. According to one implementation, matrix switch 308 maintains at least the project clock, while an upstream filter maintains the source time, converting between source and project time for all downstream filters (i.e., including the matrix switch 308). According to one implementation, the frame rate converter filter of a filter graph is responsible for converting source time to project time, and vice versa, i.e., supporting random seeks, etc. Alternatively, matrix switch 308 utilizes an integrated set of clock(s) to independently maintain project and media times.

Having introduced the architectural and operational elements of matrix switch filter 308, **Fig. 6** graphically illustrates an example filter graph implementation incorporating the innovative matrix switch 308. In accordance with the illustrated example embodiment, filter graph 600 is generated by render engine 222 in response to a user defined development project. Unlike the lengthy linear filter graphs typical of convention development systems however, filter graph 600 is shown incorporating a matrix switch filter 308 to recursively route the pre-processed content (e.g., through filters 602, 606, 610, 614 and 618, described more fully below) through a user-defined number of transform filters including, for example, transition filter(s) 620 and effects filter(s) 622. Moreover, as will be developed more fully below, the scalable nature of matrix switch filter 308 facilitates such iterative processing for any number of content threads, tracks or compositions.

1 According to one implementation, a matrix switch filter 308 can only
2 process one type of media content, of the same size and at the same frame-rate
3 (video) or modulation type/schema (audio). Thus, Fig. 6 is depicted comprising
4 pre-processing filters with a parser filter 606 to separate, independent content
5 type(s) (e.g., audio content and video content), wherein one of the media types
6 would be processed along a different path including a separate instance of matrix
7 switch 308. Thus, in accordance with the illustrated example embodiment of a
8 media processing system, processing multimedia content including audio and
9 video would utilize two (2) matrix switch filters 308, one dedicated to audio
10 processing (not shown) and one dedicated to video processing. That is not to say,
11 however, that multiple switch filters 308 could not be used (e.g., two each for
12 audio and video) for each content type in alternate implementations. Similarly, it
13 is anticipated that in alternate implementations a matrix switch 308 that accepts
14 multiple media types could well be used without deviating from the spirit and
15 scope of the present invention.

16 In addition filter graph 600 includes a decoder filter 610 to decode the
17 media content. Resize filter 614 is employed when matrix switch 308 is to receive
18 content from multiple sources, ensuring that the size of the received content is the
19 same, regardless of the source. According to one implementation, resize filter 614
20 is selectively employed in video processing paths to adjust the media size of
21 content from one or more sources to a user-defined level. Alternatively, resizer
22 filter 614 adjusts the media size to the largest size provided by any one or more
23 media sources. That is, if, for example, render engine 222 identifies the largest
24 required media size (e.g., 1270x1040 video pixels per frame) and, for any content
25 source not providing content at this size, the content is modified (e.g., stretched,

1 packed, etc.) to fill this size requirement. The frame rate converter (FRC) and
2 pack filter 618, introduced above, ensures that video content from the multiple
3 sources is arriving at the same frame rate, e.g., ten (10) frames per second. As
4 introduced above, the FRC also maintains the distinction between source time and
5 project time.

6 In accordance with one aspect of the present invention, filter graph 600 is
7 depicted utilizing a single, negotiated buffer 604, 608, 612, 616, etc. between
8 adjacent filters. In this regard, render engine 222 reduces the buffer memory
9 requirements in support of a development project.

10 From the point of pre-processing (filters 602, 606, 610, 614, 618), rather
11 than continue a linear filter graph incorporating all of the transition 620 and effect
12 622 filter(s), render engine 222 utilizes a cascade architecture, recursively passing
13 media content through the matrix switch 308 to apply to the transform filter(s)
14 (e.g., 620, 622, etc.) to complete the execution of the development project. It will
15 be appreciated by those skilled in the art that the ability to recursively pass media
16 content through one or more effect and/or transition filters provided by the matrix
17 switch filter 308 greatly reduces the perceived complexity of otherwise large filter
18 graphs, while reducing memory and computational overhead.

19 Turning to **Fig. 7**, a flow chart of an example method for generating a filter
20 graph is presented, in accordance with one aspect of the present invention. The
21 method 700 begins with block 702 wherein render engine 222 receives an
22 indication to generate a filter graph representing a user-defined development
23 project (e.g., a media editing project). According to one example implementation,
24 the indication is received from an application 224 via COM interface(s) 302.
25

1 In block 704, render engine 222 facilitates generation of the editing project,
2 identifying the number and type of media sources selected by the user. In block
3 706, based at least in part on the number and/or type of media sources, filter graph
4 manger 222 exposes source, transform and rendering filter(s) to effect a user
5 defined media processing project, while beginning to establish a programming
6 grid 406 for the matrix switch filter 308.

7 In block 708, reflecting user editing instructions, render engine 222
8 completes the programming grid 406 for matrix switch 308, identifying which
9 inputs 402 are to be coupled to which outputs 404 at particular project times.

10 Based, at least in part, on the programming grid 406 render engine 222
11 generates a matrix switch filter 308 with an appropriate number of input 402 and
12 output 404 pins to effect the project, and assembles the filter graph, block 710.

13 In block 712, to reduce the buffer memory requirements for the processing
14 project, the render engine 222 instructs the filters populating the filter graph to
15 (re)negotiate buffer memory requirements between filters. That is, adjacent filters
16 attempt to negotiate a size and attribute standard so that a single buffer can be
17 utilized to couple each an output pin of one filter to an input pin of a downstream
18 filter. An example implementation of the buffer negotiation process of block 712
19 is presented in greater detail with reference to Fig. 8.

20 Turning briefly to Fig. 8, an example method of negotiating buffer
21 requirements between adjacent filters is presented, in accordance with one
22 example implementation of the present invention. Once the final connection is
23 established to matrix switch 308, matrix switch 308 identifies the maximum buffer
24 requirements for any filter coupled to any of its pins (input 402 and/or output 404),
25 block 802. According to one implementation, the maximum buffer requirements

are defined as the lowest common multiple of buffer alignment requirements, and the maximum of all the pre-fix requirements of the filter buffers.

In block 804, matrix switch 308 selectively removes one or more existing filter connections to adjacent filters. Matrix switch 308 then reconnects all of its pins to adjacent filters using a common buffer size between each of the pins, block 806. In block 808, matrix switch 308 negotiates to be the allocator for all of its pins (402, 404). If the matrix switch 308 cannot, for whatever reason, be the allocator for any of its input pins 402 minimal loss to performance is encountered, as the buffer associated with the input pin will still be compatible with any downstream filter (i.e., coupled to an output pin) and, thus, the buffer can still be passed to the downstream filter without requiring a memory copy operation. If, however, matrix switch 308 cannot be an allocator for one of its output pins 404, media content must then be transferred to at least the downstream filter associated with that output pin using a memory copy operation, block 810.

In block 812, once the matrix switch 308 has re-established its connection to adjacent filters, render engine 222 restores the connection in remaining filters using negotiated buffer requirements emanating from the matrix switch filter 308 buffer negotiations. Once the connections throughout the filter graph have been reconnected, the process continues with block 714 of Fig. 7.

In block 714 (Fig. 7), have re-established the connections between filters, render engine 222 is ready to implement a user's instruction to execute the media processing project.

Example Operation and Implementation(s)

The matrix switch described above is quite useful in that it allows multiple inputs to be directed to multiple outputs at any one time. These input can compete for a matrix switch output. The embodiments described below permit these competing inputs to be organized so that the inputs smoothly flow through the matrix switch to provide a desired output. And, while the inventive programming techniques are described in connection with the matrix switch as such is employed in the context of multi-media editing projects, it should be clearly understood that application of the inventive programming techniques and structures should not be so limited only to application in the field of multi-media editing projects or, for that matter, multi-media applications or data streams. Accordingly, the principles about to be discussed can be applied to other fields of endeavor in which multiple inputs can be characterized as competing for a particular output during a common time period.

In the multi-media example below, the primary output of the matrix switch is a data stream that defines an editing project that has been created by a user. Recall that this editing project can include multiple different sources that are combined in any number of different ways, and the sources that make up a project can comprise audio sources, video sources, or both. The organization of the inputs and outputs of the matrix switch are made manageable, in the examples described below, by a data structure that permits the matrix switch to be programmed.

Fig. 9 shows an overview of a process that takes a user-defined editing project and renders from it a data structure that can be used to program the matrix switch.

Specifically, a user-defined editing project is shown generally at 900. Typically, when a user creates an editing project, they can select from a number of different multimedia clips that they can then assemble into a unique presentation. Each individual clip represents a *source* of digital data or a source stream (e.g., multimedia content). Projects can include one or more sources 902. In defining their project, a user can operate on sources in different ways. For example, video sources can have *transitions* 904 and *effects* 906 applied on them. A transition object is a way to change between two or more sources. As discussed above, a transition essentially receives as input, two or more streams, operates on them in some way, and produces a single output stream. An exemplary transition can comprise, for example, fading from one source to another. An effect object can operate on a single source or on a composite of sources. An effect essentially receives a single input stream, operates on it in some way, and produces a single output stream. An exemplary effect can comprise a black-and-white effect in which a video stream that is configured for presentation in color format is rendered into a video stream that is configured for presentation in black and white format. Unlike conventional effect filters, effect object 906 may well perform multiple effect tasks. That is, in accordance with one implementation, an effect object (e.g., 906) may actually perform multiple tasks on the received input stream, wherein said tasks would require multiple effect filters in a conventional filter graph system.

An exemplary user interface 908 is shown and represents what a user might see when they produce a multimedia project with software executing on a computer. In this example, the user has selected three sources A, B, and C, and has assembled the sources into a project timeline. The project timeline defines

1 when the individual sources are to be rendered, as well as when any transitions
2 and/or effects are to occur.

3 In the discussion that follows, the notion of a *track* is introduced. A track
4 can contain one or more sources or source clips. If a track contains more than one
5 source clip, the source clips cannot overlap. If source clips are to overlap (e.g.
6 fading from one source to another, or having one source obscure another), then
7 multiple tracks are used. A track can thus logically represent a layer on which
8 sequential video is produced. User interface 908 illustrates a project that utilizes
9 three tracks, each of which contains a different source. In this particular project
10 source A will show for a period of time. At a defined time in the presentation,
11 source A is obscured by source B. At some later time, source B transitions to
12 source C.

13 In accordance with the described embodiment, the user-defined editing
14 project 900 is translated into a data structure 910 that represents the project. In the
15 illustrated and described example, this data structure 910 comprises a tree
16 structure. It is to be understood, however, that other data structures could be used.
17 The use of tree structures to represent editing projects is well-known and is not
18 described here in any additional detail. Once the data structure 910 is defined, it is
19 processed to provide a data structure 912 that is utilized to program the matrix
20 switch. In the illustrated and described embodiment, data structure 912 comprises
21 a grid from which the matrix switch can be programmed. It is to be understood
22 and appreciated that other data structures and techniques could, however, be used
23 to program the matrix switch without departing from the spirit and scope of the
24 claimed subject matter.
25

1 The processing that takes place to define data structures 910 and 912 can
2 take place using any suitable hardware, software, firmware, or combination
3 thereof. In the examples set forth below, the processing takes place utilizing
4 software in the form of a video editing software package that is executable on a
5 general purpose computer.

6 7 Example Project

8 For purposes of explanation, consider Fig. 10 which shows project 908
9 from Fig. 9 in a little additional detail. Here, a time line containing numbers 0-16
10 is provided adjacent the project to indicate when particular sources are to be seen
11 and when transitions and effects (when present) are to occur. In the examples in
12 this document, the following convention exists with respect to projects, such as
13 project 908. A priority exists for video portions of the project such that as one
14 proceeds from top to bottom, the priority increases. Thus, in the Fig. 10 example,
15 source A has the lowest priority followed by source B and source C. Thus, if there
16 is an overlap between higher and lower priority sources, the higher priority source
17 will prevail. For example, source B will obscure source A from between $t = 4-8$.

18 In this example, the following can be ascertained from the project 908 and
19 time line: from time $t=0-4$ source A should be routed to the matrix switch's
20 primary output; from $t=4-12$ source B should be routed to the matrix switch's
21 primary output; from $t=12-14$ there should be a transition between source B and
22 source C which should be routed to the matrix switch's primary output; and from
23 $t=14-16$ source C should be routed to the matrix switch's primary output. Thus,
24 relative to the matrix switch, each of the sources and the transition can be
25

characterized by where it is to be routed at any given time. Consider, for example, the table just below:

| Object | Routing for a given time |
|------------|---|
| C | $t = 0-12$ (nowhere); $t = 12-14$ (transition); $t = 14-16$ (primary output) |
| B | $t = 0-4$ (nowhere); $t = 4-12$ (primary output); $t = 12-14$ (transition); $t = 14-16$ (nowhere) |
| A | $t = 0-4$ (primary output); $t = 4-16$ (nowhere) |
| Transition | $t = 0-12$ (nowhere); $t = 12-14$ (primary output); $t = 14-16$ (nowhere) |

Fig. 11 shows an exemplary matrix switch 1100 that can be utilized in the presentation of the user's project. Matrix switch 1100 comprises multiple inputs and multiple outputs. Recall that a characteristic of the matrix switch 1100 is that any of the inputs can be routed to any of the outputs at any given time. A transition element 1102 is provided and represents the transition that is to occur between sources B and C. Notice that the matrix switch includes four inputs numbered 0-3 and three outputs numbered 0-2. Inputs 0-2 correspond respectively to sources A-C, while input 3 corresponds to the output of the transition element 1102. Output 0 corresponds to the switch's primary output, while outputs 1 and 2 are routed to the transition element 1102.

The information that is contained in the table above is the information that is utilized to program the matrix switch. The discussion presented below describes but one implementation in which the information contained in the above table can be derived from the user's project time line.

Fig. 12 shows a graphic representation of an exemplary data structure 1200 that represents the project of Fig. 10. Here, the data structure comprises a traditional hierarchical tree structure. Any suitable data structure can, however, be utilized. The top node 1202 constitutes a *group* node. A *group* encapsulates a type of media. For example, in the present example the media type comprises video. Another media type is audio. The group node can have child nodes that are either tracks or composites. In the present example, three track nodes 1204, 1206, and 1208 are shown. Recall that each track can have one or more sources. If a track comprises more than one source, the sources cannot overlap. Here, all of the sources (A, B, and C) overlap. Hence, three different tracks are utilized for the sources. In terms of priority, the lowest priority source is placed into the tree furthest from the left at 1204a. The other sources are similarly placed. Notice that source C (1208a) has a transition 1210 associated with it. A transition object, in

Once a data structure representing the project has been built, in this case a hierarchical tree structure, a rendering engine processes the data structure to provide another data structure that is utilized to program the matrix switch. In the Fig. 9 example, this additional data structure is represented at 912. It will be appreciated and understood that the nodes of tree 1200 can include so-called meta information such as a name, ID, and a time value that represents when that particular node's object desires to be routed to the output, e.g. node 1204a would include an identifier for the node associating it with source A, as well as a time value that indicates that source A desires to be routed to the output from time $t = 0-8$. This meta information is utilized to build the data structure that is, in turn, utilized to program the matrix switch.

In the example about to be described below, a specific data structure in the form of a grid is utilized. In addition, certain specifics are described with respect to how the grid is processed so that the matrix switch can be programmed. It is to be understood that the specific described approach is for exemplary purposes only and is not intended to limit application of the claims. Rather, the specific approach

1 constitutes but one way of implementing broader conceptual notions embodied by
2 the inventive subject matter.

3 Figs. 13-18 represent a process through which the inventive grid is built. In
4 the grid about to be described, the x axis represents time, and the y axis represents
5 layers in terms of priority that go from lowest (at the top of the grid) to highest (at
6 the bottom of the grid). Every row in the grid represents the video layer.
7 Additionally, entries made within the grid represent output pins of the matrix
8 switch. This will become apparent below.

9 The way that the grid is built in this example is that the rendering engine
10 does a traversal operation on the tree 1200. In this particular example, the
11 traversal operation is known as a “depth-first, left-to-right” traversal. This
12 operation will layerize the nodes so that the leftmost track or source has the lowest
13 priority and so on. Doing the above-mentioned traversal on tree 1200 (Fig. 12),
14 the first node encountered is node 1204 which is associated with source A. This is
15 the lowest priority track or source. A first row is defined for the grid and is
16 associated with source A. After the first grid row is defined, a grid entry is made
17 and represents the time period for which source A desires to be routed to the
18 matrix switch’s primary output.

19 Fig. 13 shows the state of a grid 1300 after this first processing step.
20 Notice that from time $t = 0-8$, a “0” has been placed in the grid. The “0”
21 represents the output pin of the matrix switch—in this case the primary output.
22 Next, the traversal encounters node 1206 (Fig. 12) which is associated with source
23 B. A second row is thus defined for the grid and is associated with source B.
24 After the second grid row is defined, a grid entry is made and represents the time
25

1 period for which source B desires to be routed to the matrix switch's primary
2 output.

3 Fig. 14 shows the state of grid 1300 after this second processing step.
4 Notice that from time $t = 4-14$, a "0" has been placed in the grid. Notice at this
5 point that something interesting has occurred which will be resolved below. Each
6 of the layers has a common period of time (i.e. $t = 4-8$) for which it desires to be
7 routed to the matrix switch's primary output. However, because of the nature of
8 the matrix switch, only one input can be routed to the primary output at a time.
9 Next, the traversal encounters node 1208 (Fig. 12) which is associated with source
10 C. In this particular processing example, a rule is defined that sources on tracks
11 are processed before transitions on the tracks are processed because transitions
12 operate on two objects that are beneath them. A third row is thus defined for the
13 grid and is associated with source C. After the third row is defined, a grid entry is
14 made and represents the time period for which source C desires to be routed to the
15 matrix switch's primary output.

16 Fig. 15 shows the state of grid 1300 after this third processing step. Notice
17 that from time $t = 12-16$, a "0" has been placed in the grid. Next, the traversal
18 encounters node 1210 (Fig. 12) which corresponds to the transition. Thus, a fourth
19 row is defined in the grid and is associated with the transition. After the fourth
20 row is defined, a grid entry is made and represents the time period for which the
21 transition desires to be routed to the matrix switch's primary output.

22 Fig. 16 shows the state of grid 1300 after this fourth processing step.
23 Notice that from time $t = 12-14$, a "0" has been placed in the grid for the transition
24 entry. The transition is a special grid entry. Recall that the transition is
25 programmed to operate on two inputs and provide a single output. Accordingly,

starting at the transition entry in the grid and working backward, each of the entries corresponding to the same tree level are examined to ascertain whether they contain entries that indicate that they want to be routed to the output during the same time that the transition is to be routed to the output. If grid entries are found that conflict with the transition's grid entry, the conflicting grid entry is changed to a value that corresponds to an output pin that serves as an input to the transition element 1102 (Fig. 11). This is essentially a redirection operation. In the illustrated grid example, the transition first finds the level that corresponds to source C. This level conflicts with the transition's grid entry for the time period $t = 12-14$. Thus, for this time period, the grid entry for level C is changed to a switch output that corresponds to an input for the transition element. In this example, a "2" is placed in the grid to signify that for this given time period, this input is routed to output pin 2. Similarly, continuing up the grid, the next level that conflicts with the transition's grid entry is the level that corresponds to source B. Thus, for the conflicting time period, the grid entry for level B is changed to a switch output that corresponds to an input for the transition element. In this example, a "1" is placed in the grid to signify that for this given time period, this input is routed to output pin 1 of the matrix switch.

Fig. 17 shows the state of the grid at this point in the processing. Next, a pruning function is implemented which removes any other lower priority entry that is contending for the output with a higher priority entry. In the example, the portion of A from $t=4-8$ gets removed because the higher priority B wants the output for that time.

Fig. 18 shows the grid with a cross-hatched area that signifies that portion of A's grid entry that has been removed.

At this point, the grid is in a state in which it can be used to program the matrix switch. The left side entries -- A, B, C, and TRANS represent input pin numbers 0, 1, 2, and 3 (as shown) respectively, on the matrix switch shown in Fig. 11. The output pin numbers of the matrix switch are designated at 0, 1, and 2 both on the switch in Fig. 11 and within the grid in Fig. 18. As one proceeds through the grid, starting with source A, the programming of the matrix switch can be ascertained as follows: A is routed to output pin 0 of the matrix switch (the primary output) from $t = 0-4$. From $t = 4-16$, A is not routed to any output pins. From $t = 0-4$, B is not routed to any of the output pins of the matrix switch. From $t = 4-12$, B is routed to the primary output pin 0 of the matrix switch. From $t = 12-14$, B is routed to output pin 1 of the matrix switch. Output pin 1 of the matrix switch corresponds to one of the input pins for the transition element 1102 (Fig. 11). From $t = 14-16$, B is not routed to any of the output pins of the matrix switch. From $t = 0-12$, C is not routed to any of the output pins of the matrix switch. From $t = 12-14$, C is routed to output pin 2 of the matrix switch. Output pin 2 of the matrix switch corresponds to one of the input pins for the transition element 302 (Fig. 3). From $t = 12-14$ the transition element (input pin 3) is routed to output pin 0. From $t = 14-16$, C is routed to output pin 0 of the matrix switch.

As alluded to above, one of the innovative aspects of the matrix switch 308 is its ability to seek to any point in a source, without having to process the intervening content serially through the filter. Rather, matrix switch 308 identifies an appropriate transition point and dumps at least a subset of the intervening content, and continues processing from the sought point in the content.

The ability of the matrix switch 308 to seek to any point in the media content gives rise to certain performance enhancement heretofore unavailable in

1 computer implemented media processing systems. For example, generation of a
2 filter graph by render engine 222 may take into account certain performance
3 characteristics of the media processing system which will execute the user-defined
4 media processing project. In accordance with this example implementation,
5 render engine 222 may access and analyze the system registry of the operating
6 system, for example, to ascertain the performance characteristics of hardware
7 and/or software elements of the computing system implementing the media
8 processing system, and adjust the filter graph construction to improve the
9 perceived performance of the media processing system by the user. Nonetheless,
10 there will always be a chance that a particular instance of a filter graph will not be
11 able to process the media stream fast enough to provide the desired output at the
12 desired time, i.e., processing of the media stream bogs down leading to delays at
13 the rendering filter. In such a case, matrix switch 308 will recognize that it is not
14 receiving media content at the appropriate project time, and may skip certain
15 sections of the project in an effort to "catch-up" and continue the remainder of the
16 project in real time. According to one implementation, when matrix switch 308
17 detects such a lag in processing, it will analyze the degree of the lag and issue a
18 seek command to the source (through the source processing chain) to a future
19 point in the project, where processing continues without processing any further
20 content prior to the seeked point.

21 Thus, for the editing project depicted in Fig. 10, the processing described
22 above first builds a data structure (i.e. data structure 1200 in Fig. 12) that
23 represents the project in hierarchical space, and then uses this data structure to
24 define or create another data structure that can be utilized to program the matrix
25 switch.

Fig. 19 is a flow diagram that describes steps in a method in accordance with the described embodiment. The method can be implemented in any suitable hardware, software, firmware, or combination thereof. In the illustrated and described embodiment, the method is implemented in software.

Step 1900 provides a matrix switch. An exemplary matrix switch is described above. Step 1902 defines a first data structure that represents the editing project. Any suitable data structure can be used, as will be apparent to those of skill in the art. In the illustrated and described embodiment, the data structure comprises a hierarchical tree structure having nodes that can represent tracks (having one or more sources), composites, transitions and effects. Step 1904 processes the first data structure to provide a second data structure that is configured to program the matrix switch. Any suitable data structure can be utilized to implement the second data structure. In the illustrated and described embodiment, a grid structure is utilized. Exemplary processing techniques for processing the first data structure to provide the second data structure are described above. Step 1906 then uses the second data structure to program the matrix switch.

Example Project with a Transition and an Effect

Consider project 2000 depicted in Fig. 20. In this project there are three tracks, each of which contains a source, i.e. source A, B and C. This project includes an effect applied on source B and a transition between sources B and C. The times are indicated as shown.

As the user creates their project, a data structure representing the project is built. Fig. 21 shows an exemplary data structure in the form of a hierarchical tree

In building the grid for project 2000, the following rule is employed for effects. An effect, in this example, is a one-input/one-output object that is applied to one object—in this case source B. When the effect is inserted into the grid, it looks for any one object beneath it in priority that has a desire to be routed to the primary output of the matrix switch at the same time. When it finds a suitable object, it redirects that object's output from the matrix switch's primary output to an output associated with the effect.

As an example, consider Fig. 22 and the grid 2200. At this point in the processing of tree 2100, the rendering engine has incorporated entries in the grid corresponding to sources A, B and the effect. It has done so by traversing the tree 2100 in the above-described way. In this example, the effect has already looked for an object beneath it in priority that is competing for the primary output of the matrix switch. It found an entry for source B and then redirected B's grid entry to a matrix switch output pin that corresponds to the effect—here output pin 1.

As the render engine 222 completes its traversal of tree 2100, it completes the grid. Fig. 23 shows a completed grid 2200. Processing of the grid after that which is indicated in Fig. 22 takes place substantially as described above with respect to the first example. Summarizing, this processing though: after the effect is entered into the grid and processed as described above, the traversal of tree 2100

09/23/2000 12:06:00

next encounters the node associated with source C. Thus, a row is added in the grid for source C and an entry is made to indicate that source C desires the output from $t = 12-16$. Next, the tree traversal encounters the node associated with the transition. Accordingly, a row is added to the grid for the transition and a grid entry is made to indicate that the transition desires the output from $t = 12-14$. Now, as described above, the grid is examined to find two entries, lower in priority than the transition and located at the same tree level as the transition, that compete for the primary output of the matrix switch. Here, those entries correspond to the grid entries for the effect and source C that occur from $t = 12-14$. These grid entries are thus redirected to output pins of the matrix switch 308 that correspond to the transition—here pins 2 and 3 as indicated. Next, the grid is pruned which, in this example, removes a portion of the grid entry corresponding to source A for $t = 4-8$ because of a conflict with the higher-priority entry for source B.

Fig. 24 shows the resultant matrix switch that has been built and configured as the grid was being processed above. At this point, the grid can be used to program the matrix switch. From the grid picture, it is very easy to see how the matrix switch 308 is going to be programmed. Source A will be routed to the matrix switch's primary output (pin 0) from $t = 0-4$; source B will be redirected to output pin 1 (effect) from $t = 4-14$ and the effect on B will be routed to the output pin 0 from $t = 4-12$. From $t = 12-14$, the effect and source C will be routed to output pins corresponding to the transition (pins 2 and 3) and, accordingly, during this time the transition (input pin 4) will be routed to the primary output (output pin 0) of the matrix switch. From $t = 14-16$, source C will be routed to the primary output of the matrix switch.

1 It will be appreciated that as the software, in this case the render engine
2 222, traverses the tree structure that represents a project, it also builds the
3 appropriate graphs and adds the appropriate filters and graphs to the matrix switch.
4 Thus, for example, as the render engine 222 encounters a tree node associated with
5 source A, in addition to adding an entry to the appropriate grid, the software builds
6 the appropriate graphs (i.e. collection of linked filters), and associates those filters
7 with an input of the matrix switch. Similarly, when the render engine 222
8 encounters an effect node in the tree, the software obtains an effect object or filter
9 and associates it with the appropriate output of the matrix switch. Thus, in the
10 above examples, traversal of the tree structure representing the project also enables
11 the software to construct the appropriate graphs and obtain the appropriate objects
12 and associate those items with the appropriate inputs/outputs of the matrix switch
13 308. Upon completion of the tree traversal and processing of the grid, an
14 appropriate matrix switch has been constructed, and the programming (i.e. timing)
15 of inputs to outputs for the matrix switch has been completed.

16 17 **Treatment of "blanks" in a Project**

18 There may be instances in a project when a user leaves a blank in the
19 project time line. During this blank period, no video or audio is scheduled for
20 play.

21 Fig. 25 shows a project that has such a blank incorporated therein. If there
22 is such a blank left in a project, the software is configured to obtain a "black"
23 source and associate the source with the matrix switch at the appropriate input pin.
24 The grid is then configured when it is built to route the black source to the output
25 at the appropriate times and fade from the black (and silent) source to the next

source at the appropriate times. The black source can also be used if there is a transition placed on a source for which there is no additional source from which to transition.

Audio Mixing

In the examples discussed above, sources comprising video streams were discussed. In those examples, at any one time, only two video streams were combined into one video stream. However, each project can, and usually does contain an audio component. Alternately, a project can contain only an audio component. The audio component can typically comprise a number of different audio streams that are combined. The discussion below sets forth but one way of processing and combining audio streams.

In the illustrated example, there is no limit on the number of audio streams that can be combined at any one time.

Suppose, for example, there is an audio project that comprises 5 tracks, A-E. Fig. 26 shows an exemplary project. The shaded portions of each track represent the time during which the track is not playing. So, for example, at $t=0-4$, tracks B, D, and E are mixed together and will play. From $t = 4-10$, tracks A-E are mixed together and will play, and the like.

Fig. 27 shows the grid for this project at 2700. Since we are dealing with this composition now, all of the effects and transitions including the audio mixing are only allowed to affect things in this composition. Thus, there is the concept of a boundary 2702 that prevents any actions or operations in this composition from affecting any other grid entries. Note that there are other entries in the grid and

1 that the presently-illustrated entries represent only those portions of the project
2 that relate to the audio mixing function.

3 Grid 2700 is essentially set up in a manner similar to that described above
4 with respect to the video projects. That is, for each track, a row is added to the
5 grid and a grid entry is made for the time period during which the source on that
6 track desires to be routed to the primary output of the matrix switch. In the
7 present example, grid entries are made for sources A-E. Next, in the same way
8 that a transition or effect was allocated a row in the grid, a "mix" element is
9 allocated a row in the grid as shown and a grid entry is made to indicate that the
10 mix element desires to be routed to the primary output of the matrix switch for a
11 period of time during which two or more sources compete for the matrix switch's
12 primary output. Note that in this embodiment, allocation of a grid row for the mix
13 element can be implied. Specifically, whereas in the case of a video project,
14 overlapping sources simply result in playing the higher priority source (unless the
15 user defines a transition between them), in the audio realm, overlapping sources
16 are treated as an implicit request to mix them. Thus, the mix element is allocated a
17 grid row any time there are two or more overlapping sources.

18 Once the mix element is allocated into the grid, the grid is processed to
19 redirect any conflicting source entries to matrix switch output pins that correspond
20 to the mix element. In the above case, redirection of the grid entries starts with pin
21 3 and proceeds through to pin 7. The corresponding matrix switch is shown in
22 Fig. 28. Notice that all of the sources are now redirected through the mix element
23 which is a multi-input/one output element. The mix element's output is fed back
24 around and becomes input pin 15 of the matrix switch. All of the programming of
25 the matrix switch is now reflected in the grid 2700. Specifically, for the indicated

1 time period in the grid, each of the sources is routed to the mix element which, in
2 turn, mixes the appropriate audio streams and presents them to the primary output
3 pin 0 of the matrix switch.
4

5 Compositions

6 There are situations that can arise when building an editing project where it
7 would be desirable to apply an effect or a transition on just a subset of a particular
8 project or track. Yet, there is no practicable way to incorporate the desired effect
9 or transition. In the past, attempts to provide added flexibility for editing projects
10 have been made in the form of so called "bounce tracks", as will be appreciated
11 and understood by those of skill in the art. The use of bounce tracks essentially
12 involves processing various video layers (i.e. tracks), writing or moving the
13 processed layers or tracks to another location, and retrieving the processed layers
14 when later needed for additional processing with other layers or tracks. This type
15 of processing can be slow and inefficient.

16 To provide added flexibility and efficiency for multi-media editing projects,
17 the notion of a *composite or composition* is introduced. A composite or
18 composition can be considered as a representation of an editing project as a single
19 track. Recall that editing projects can have one or more tracks, and each track can
20 be associated with one or more sources that can have effects applied on them or
21 transitions between them. In addition, compositions can be nested inside one
22 another.
23
24
25

Example Project with Composite

Consider, for example, Fig. 29 which illustrates an exemplary project 2900 having a composition 2902. In this example, composition 2902 comprises sources B and C and a transition between B and C that occurs between $t = 12-14$. This composition is treated as an individual track or layer. Project 2900 also includes a source A, and a transition between source A and composition 2902 at $t = 4-8$. It will be appreciated that compositions can be much more complicated than the illustrated composition, which is provided for exemplary purposes only. Compositions are useful because they allow the grouping of a particular set of operations on one or more tracks. The operation set is performed on the grouping, and does not affect tracks that are not within the grouping. To draw an analogy, a composition is similar in principle to a mathematical parenthesis. Those operations that appear within the parenthesis are carried out in conjunction with those operations that are intended to operate of the subject matter of the parenthesis. The operations within the parenthesis do not affect tracks that do not appear within the parenthesis.

In accordance with the processing that is described above in connection with Fig. 19, a first data structure is defined that represents the editing project. Fig. 30 shows an exemplary data structure 3000 in the form of a hierarchical tree structure. In this example, group node 3002 includes two children—track node 3004 and composite node 3006. Track node 3004 is associated with source A. Composite node 3006 includes two children—track nodes 3008 and 3010 that are respectively associated with sources B (3008a) and C (3010a). A transition T2 (3012) is applied on source C and a transition T1 (3014) is applied on composition 3006.

1 Next, data structure 3000 is processed to provide a second data structure
2 that is configured to program the matrix switch. Note that as the data structure is
3 being programmed, a matrix switch is being built and configured at the same time.
4 In this example, the second data structure comprises a grid structure that is
5 assembled in much the same way as was described above. There are, however,
6 some differences and, for purposes of understanding, the complete evolution of the
7 grid structure is described here. In the discussion that follows, the completed
8 matrix switch is shown in Fig. 38.

9 When the rendering engine initiates the depth-first, left-to-right traversal of
10 data structure 3000, the first node it encounters is track node 3004 which is
11 associated with source A. Thus, a first row of the grid is defined and a grid entry
12 is made that represents the time period for which source A desires to be routed to
13 the matrix switch's primary output pin.

14 Fig. 31 shows the state of a grid 3100 after this first processing step. Next
15 the traversal of data structure 3000 encounters the composite node 3006. The
16 composite node is associated with two tracks—track 3008 and track 3010. Track
17 3008 is associated with source B. Accordingly, a second row of the grid is defined
18 and a grid entry is made that represents the time period for which source B desires
19 to be routed to the matrix switch's primary output pin. Additionally, since B is a
20 member of a composition, meta-information is contained in the grid that indicates
21 that this grid row defines one boundary of the composition. This meta-
22 information is graphically depicted with a bracket that appears to the left of the
23 grid row.

24 Fig. 32 shows the state of grid 3100 after this processing step. Next, the
25 traversal of data structure 3000 encounters node 3010 which is associated with

1 source C. Thus, a third row of the grid is added and a grid entry is made that
2 represents the time period for which source C desires to be routed to the matrix
3 switch's primary output pin.

4 Fig. 33 shows the state of grid 3100 after this processing step. Notice that
5 the bracket designating the composition now encompasses the grid row associated
6 with source C. The traversal next encounters node 3012 which is the node
7 associated with the *second* transition T2. Thus, as in the above example, a grid
8 row is added for the transition and a grid entry is made that represents the time
9 period for which the transition desires to be routed to the matrix switch's primary
10 output pin.

11 Fig. 34 shows the state of grid 3100 after this processing step. Notice that
12 the bracket designating the composition is now completed and encompasses grid
13 row entries that correspond to sources B and C and the transition between them.
14 Recall from the examples above that a transition, in this example, is programmed
15 to operate on two inputs and provide a single output. In this instance, and because
16 the transition occurs within a composition, the transition is constrained by a rule
17 that does not allow it to operate on any elements outside of the composition.
18 Thus, starting at the transition entry and working backward through the grid,
19 entries at the same tree level and within the composition (as designated by the
20 bracket) are examined to ascertain whether they contain entries that indicate that
21 they want to be routed to the output during the same time that the transition is to
22 be routed to the output. Here, both of the entries for sources B and C have
23 portions that conflict with the transition's entry. Accordingly, those portions of
24 the grid entries for sources B and C are redirected or changed to correspond to
25

1 output pins that are associated with a transition element that corresponds to
2 transition T2.

3 Fig. 35 shows the state of grid 3100 after this processing step. The
4 traversal next encounters node 3014 which is the node that is associated with the
5 transition that occurs between source A and composition 2902 (Fig. 29).
6 Processing of this transition is similar to processing of the transition immediately
7 above except for the fact that the transition does not occur within the composition.
8 Because the transition occurs between the composition and another source, one of
9 the inputs for the transition will be the composition, and one of the inputs will be
10 source A (which is outside of the composition). Thus, a grid row is added for this
11 transition and a grid entry is made that represents the time period for which the
12 transition desires to be routed to the matrix switch's primary output pin.

13 Fig. 36 shows the state of grid 3100 after this processing step. At this point
14 then, the grid is examined for entries that conflict with the entry for transition T1.
15 One conflicting grid entry is found for the row that corresponds to source B (inside
16 the composition) and one that corresponds to source A (outside the composition).
17 Accordingly, those portions of the grid row that conflict with transition T1 are
18 changed or redirected to have values that are associated with output pins of the
19 matrix switch that are themselves associated with a transition element T1. In this
20 example, redirection causes an entry of "3" and "4" to be inserted as shown.

21 Fig. 37 shows the state of grid 3100 after this processing step. If necessary,
22 a pruning operation would further ensure that the grid has no competing entries for
23 the primary output of the matrix switch. The associated input pin numbers of the
24 matrix switch are shown to the left of grid 3100.
25

Fig. 38 shows a suitably configured matrix switch that has been build in accordance with the processing described above. Recall that, as data structure 3000 (Fig. 30) is processed by the rendering engine, a matrix switch is built and configured in parallel with the building and processing of the grid structure that is utilized to program the matrix switch. From the matrix switch and grid 3100 of Fig. 37, the programming of the switch can be easily ascertained.

Fig. 38a shows an exemplary data structure that represents a project that illustrates the usefulness of composites. In this example, the project can mathematically be represented as follows:

$$(Fx\text{-noisy } (A \text{ Tx-Blend } B)) \text{ Tx-Blend } C$$

Here, an effect (noisy) is applied to A blended with B, the result of which is applied to a blend with C. The composite in this example allows the grouping of the things beneath it so that the effect (noisy), when it is applied, is applied to everything that is beneath it. Notice that without the composite node, there is no node where an effect can be applied that will affect (A Tx-Blend B). Hence, in this example, operations that appear within the parenthesis are carried out on tracks that appear within the parenthesis. Those operations do not affect tracks that are not within the parenthesis.

Fig. 39 is a flow diagram that described steps in a method in accordance with one embodiment. The method can be implemented in any suitable hardware, software, firmware, or combination thereof. In the presently-described example, the method is implemented in software.

Step 3900 defines a multimedia editing project that includes at least one composite. The composite represents multiple tracks as a single track for purposes of the processing described just below. It is important to note that, in the processing described just below, and because of the use of composites, the extra processing that is required by bounce tracks is avoided (i.e. operating on two tracks, moving the operation result to another location, and retrieving the operation result when later needed). This reduces the processing time that is required to render a multi-media project. Step 3902 defines a first data structure that represents the editing project. Any suitable data structure can be utilized. In the present example, a data structure in the form of a hierarchical tree is utilized. An exemplary tree is shown in Fig. 30. Step 3904 processes the first data structure to provide a second data structure that is configured to program a matrix switch. In the illustrated example, the second data structure comprises a grid structure. Exemplary processing is described in the context of Figs. 30-37. Step 3906 then programs the matrix switch using the second data structure.

Implementing Dynamic Properties on Objects that Only Support Static Properties

Computer-implemented objects typically have properties associated with them. Many different types of properties can be associated with such objects. For example, consider a computer-implemented object in the form of a ball. The ball can have various properties such as color, direction of movement, speed, etc. These properties typically have values associated with them. For example, for the property "color", property values might include blue, orange, red, and yellow. For the property "direction", property values might include x-direction, y-direction, and z-direction.

Many objects have so-called static properties whose values can only be set at a current time. In essence, these types of objects have to be notified to change their property values currently. These types of objects are not pre-programmable to change their property values at some point in the future. Dynamic properties are properties whose values can change at certain times. An object such as a ball that supports dynamic properties can, for example, be pre-programmed to change its color, direction, speed, and the like, dynamically at any time in the future. That is, such objects can be preprogrammed to change their property values.

It would be desirable to be able to impart to objects that support only static properties characteristics such that they behave like they support dynamic properties. That is, it would be desirable to be able to pre-program objects that support only static properties.

Fig. 40 is a block diagram of a system that can be utilized, in accordance with the described embodiment, to impart to objects that support only static properties, characteristics that enable them to behave in a way that appears as if they support dynamic properties.

In the illustrated example, an object 4000 is provided and constitutes any object that can support only static properties. Accordingly, a set of static properties 4002 is shown. It will be appreciated that any suitable number of objects such as object 4000 can be provided. In addition, any number and/or type of suitable static properties can be supported by the object. For purposes of this example, however, assume that object 4000 represents a ball and that the ball has properties that include color, directions of movement and speed.

A helper object 4004 is provided and is used in connection with object 4000 to, in a sense, imitate or simulate dynamic properties. The result of the interaction

1 of the helper object 4004 and object 4000 (which does not support dynamic
2 properties) is an object 4000 that *appears* as if it supports dynamic properties. In
3 functioning to “imitate” dynamic properties, helper object 4004 can keep track of
4 the time, various property value changes that are to be made on object 4000, and
5 the time at which the property value changes are to be made. Helper object 4004
6 then notifies object 4000 at the appointed time, so that the property value can be
7 changed.

8 Thus, in the described embodiment, an object that does not support
9 dynamic properties is made to appear as if it supports dynamic properties through
10 the use of and interaction with a helper object. The helper object can maintain
11 various property data that it then uses to effect a property value change on its
12 associated object. The property data can include, without limitation, the time
13 when the change is to take effect, type of property value change, and how to effect
14 the change. In this manner, property values and changes in those values can be
15 pre-programmed.

16 In the illustrated and described embodiment, helper object 4004 makes use
17 of data structures that assist it in its job. For each property whose values are to be
18 changed, a set of structures is defined. Each structure comprises entries for time
19 (i.e. the time that a property value change is to take place), a variant for the value
20 of the property, and an entry for how the change is to take place (e.g. immediately,
21 or in some interpolated fashion). Thus, in the Fig. 40 example, structure array
22 4006 includes four sets of structures designated set 1, set 2, set 3, and set 4. Each
23 set is associated with a different property whose value can be changed on an object
24 that supports only static properties. For example, one set each of structures might
25 be associated with an object’s speed, color, and x/y direction of movement.

1 Consider the following example where object 4000 comprises a ball.
2 Consider that, for the ball, we want the helper object to cause the ball to be red at
3 time 0, change immediately to blue at time 2, and blend into yellow at time 4. An
4 exemplary data structure that can enable this to be done is shown in Fig. 40. In
5 this example, the data structure “(0, Red, Jump)” indicates that at time 0, the ball
6 is to immediately (i.e. “jump to”) be red; the structure “(2, Blue, Jump)” indicates
7 that at time 2, the ball is to immediately be blue; and the structure “(4, Yellow,
8 Interpolate)” indicates that at time 4, the ball is to change in a linear fashion (i.e.
9 interpolate) into yellow from blue.

10 The helper object 4004 is programmed (or pre-programmed) with the
11 various data structures that define the desired properties, their value changes, and
12 the time and manner in which the value change is to take place. The helper object
13 keeps track of the time, by for example, being called or otherwise notified of the
14 time. At the appropriate times, the helper object, using the array of structures,
15 calls the object whose property values are desired to be changed so that the
16 property values can be changed. In the present example, at time 0, the helper
17 object calls object 4000 or a property object on the object itself, and causes the
18 property value for the color property to be set to “red”. At time 2, the helper
19 object 4004 calls the object 4000 and causes the property value for the color
20 property to be set to “blue”. At time 4, the helper object calls the object 4000 and
21 causes the property value for the color property to interpolate from its previous
22 value (i.e. blue) to the present value, i.e. yellow.

23 Thus, object 4000 appears as if it supports dynamic properties when, in
24 fact, it only supports static properties.
25

As another example, consider Fig. 41. In this example a ball 4100 has directional properties that allows it to move within a coordinate system in both the x and y directions. The ball constitutes an object that supports only static properties, i.e. it cannot be pre-programmed for movement in the future. The coordinates range from 0-200 in both the x and y directions as shown. Each property (movement in the y-direction and movement in the x-direction) is associated with a set of data structures as indicated generally at 4102. In the present example, at time 0, the ball is located at x=0, y=100; at time 2, the ball jumps to x=100 and maintains its y position at 100. At time 4, the ball's position is interpolated (linearly) from x=100 to x=200, and from y=100 to y=200.

Fig. 42 is a flow diagram that describes steps in a method in accordance with the described embodiment. The method can be implemented in any suitable hardware, software, firmware or combination thereof. In the illustrated example, certain steps are implemented in software. The illustrated method can relieve a top level application from the burden of having to set object properties over and over again by keeping a thread running. The top level application relies on the helper object to know all of the properties that need to be changed or set and the time at which to change or set the properties. The helper object will then do the work involved with changing or setting the properties. This includes having a thread running and continuously setting or changing the properties as instructed by the application. In performing its job, the helper object can access a clock that the application is using so that it knows what time it is so that it can, accordingly, set or change the right property.

Step 4200 provides one or more objects that support only static properties. These objects can be provided by an application executing on a suitable computer

processor. Step 4202 provides at least one programmable helper object. The helper object can be provided by the application program. The helper object is desirably configured to be used to effect property value changes on the objects that support only static properties. Step 4204 programs the helper object with property data that is to be used by the helper object to effect one or more property value changes on one or more of the objects that support only static properties. This step can be implemented by an application program accepting input from a user that defines the property data. Specific examples of property data are given above and can include, without limitation, time when the property value change is to take effect, type of property value change, and how to effect the property value change. The property data can be organized in any suitable way. For example, in the discussion above, an array of data structures is used to hold the property data. Each structure array has one or more sets of data structures, and each set of data structures is associated with a property that is to be changed. It is to be appreciated, however, that any suitable method, structure, or technique of effecting the property changes can be used. Step 4206 then calls, with the helper object(s), one or more of the objects that support only static properties to effect the property value change on the object(s). In the illustrated and described embodiment, the helper object is called with the current time so that it knows when to call the objects whose property values it desires to change.

Specific Example

The inventive helper object can be used in many contexts where it is desirable to impart to objects that support only static properties, characteristics or behavior that appears dynamic in nature. The helper object can relieve the human

1 programmer of a great burden which, in the past, has required programmers to
2 specifically provide the software code (including timing) to implement all of the
3 property value changes. One particularly useful context for application of the
4 above-described techniques is in the area of multi-media and, in particular, the
5 editing of multi-media projects.

6 Fig. 43 shows a matrix switch 4300 that has been built as described above
7 and, as shown, is configured to effect a transition between two multi-media
8 streams. To perform that task, a transition object 4302 is provided. The transition
9 object is shown to include a helper object 4304 having a structure array, and an
10 object 4306 that supports only static properties. Object 4306 is the actual
11 transform that performs the desired transition and, in this example, is implemented
12 as a DirectX transform, although any suitable transform can be used.

13 In this example, transition object 4302 has a property called "percent
14 complete" and represents how complete the transition is for a given project time.
15 There are different percentages (i.e. values) of completion that vary as the project
16 time progresses. For example, at time 1, the transition may be 1% complete, at
17 time 2 the transition may be 3% complete and the like. Object 4306 supports only
18 static properties and, hence, is called by the helper object 4304 during the course
19 of a transition and told, by the helper object, to render a transition at a particular
20 percentage of completion. The helper object 4304 is programmed by data that is
21 received from one or more of the matrix switch, the grid and filter graphs that are
22 assembled to complete the project. This information is in a form that is not
23 understood by the object 4306 that performs the actual transition. Accordingly, the
24 helper object 4304 acts as an intermediary in that it receives programming
25 information that describes when, how, and what properties and values are to be

changed. The helper object then translates this programming information into instructions that are specific to and understood by object 4306 that performs the actual transition.

Accordingly, in this example, helper object 4304 defines an intermediate level that provides the ability to simulate pre-programmed dynamic properties on an object (i.e. object 4306) that otherwise does not have the capability to have dynamic properties.

Conclusion

The described embodiments can be used to provide improvements over previous multi-media editing systems. Various efficiencies are achieved that reduce the processing times and can thereby improve the user experience when using multi-media project editing software applications.

Although the invention has been described in language specific to structural features and/or methodological steps, it is to be understood that the invention defined in the appended claims is not necessarily limited to the specific features or steps described. Rather, the specific features and steps are disclosed as preferred forms of implementing the claimed invention.